Profiling Composable HPC Data Services WIP@PDSW, 2019

Srinivasan Ramesh Allen D. Malony

University of Oregon

Ο

Philip H. Carns Robert Ross Shane Snyder Argonne National Laboratory



Data Services: Managing Heterogeneity and Change



- Difficult to build **custom data services** efficiently:
 - Lots of moving parts
 - Need to dynamically adapt to changing application patterns
- Debugging performance problems is hard:
 - Numerous attempts at debugging microservices: Dapper@Google, Stardust, X-Trace, etc
 - We take inspiration from these

Mochi: Composable Data Services



Mobject service: An object store

*Image credits: Matthieu Dorier, Argonne National Laboratory

- Mochi data services are built by composing *microservices:*
 - RPC for control
 - RDMA for data movement
- Mochi's building blocks:
 - Mercury, Argobots, Margo
- Performance Analysis in Mochi:
 - Build performance analysis capability directly into Mochi:
 - Available out-of-the-box!

Mochi: Performance Analysis

Mobject service: Call path profiling

Cumulative Time



Call path profiling:

- We track the time spent in various *call paths* within the service:
 - A->C->D is a different call path from B->C->D
- Key idea: Each microservice stores and forwards RPC call path ancestry
- Time, call count, resource-level usage statistics updated at four instrumentation points: Client send/receive, Server send/receive
- What performance questions do we hope to answer?

Call Path Profiling: Detecting Load Imbalance

• Performance question: For a given call path, what is the *distribution* of call path times and counts in origin/target entities?

mobject_read_op: Raw distribution of call times across all origin (client) entities



Overloaded server: Large variation in response time

Raw Cumulative Time: Origin

Raw Cumulative Time: Origin

Multi-threaded server: Better read perf. and response time

Tracing: Detecting Resource-Level Inefficiencies

- Margo servers spawn a new Argobot User-Level-Task (ULT) for every incoming RPC request
 - Size of pool of tasks waiting to run is a measure of load and responsiveness of system
- We perform request tracing at the 4 instrumentation points previously described:
 - We collect Argobot pool size info, memory usage along request path
 - This enables correlation of call path behaviour with resource usage on node

mobject_read_op: Max number of pending Argobot ULT's along request path



Overloaded server: Pending tasks are stacking up



Multi-threaded server: Reduction in number of pending tasks